03-Java-vs-C_en

System-Level Programming

3 Java/Python vs. C – Some Examples

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http://sys.cs.fau.de/lehre/ss25



```
#include <stdio.h>
int main(int argc, char **argv) {
  /* greet user */
  printf("Hello World!\n");
  return 0;
```

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int main(int argc, char **argv) {
  /* greet user */
  printf("Hello World!\n");
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```

Compilation and execution (on a UNIX system)

```
~> gcc -o hello hello.c
~> ./hello
Hello World!
~>
```

Not that complicated at all :-)





```
#include <stdio.h>
int main(int argc, char **argv) {
  /* greet user */
  printf("Hello World!\n");
  return 0:
```

The most famous program of the world in **Java**

```
import java.lang.System;
class Hello {
  public static void main(String[] args) {
    /* greet user */
    System.out.println("Hello World!");
    return:
```



```
#include <stdio.h>
int main(int argc, char **argv) {
  /* greet user */
  printf("Hello World!\n");
  return 0:
```

C: A C program starts with main(), a global function of type int. which is defined in exactly one file.

The most famous program of the world in **Java**

```
import java.lang.System;
class Hello {
  public static void main(String[] args) {
    /* greet user */
    System.out.println("Hello World!");
    return:
```

Java: Each Java program starts with the function main(), a static method of type void, which is defined in exactly one class.



```
#include <stdio.h>
int main(int argc, char **argv) {
  /* greet user */
  printf("Hello World!\n");
  return 0:
```

```
C: <no counterpart>
```

The most famous program of the world in **Java**

```
import java.lang.System;
class Hello {
  public static void main(String[] args) {
    /* greet user */
    System.out.println("Hello World!");
    return:
```

Java: Each Java program consists of at least one class.



```
#include <stdio.h>
int main(int argc, char **argv) {
  /* greet user */
  printf("Hello World!\n");
  return 0:
```

C: The output of the string takes place due to the function $printf(). (\n \rightarrow new line)$

The most famous program of the world in **Java**

```
import java.lang.System;
class Hello {
  public static void main(String[] args) {
    /* greet user */
    System.out.println("Hello World!");
    return:
```

Java: The output of one string takes place in the method println() from the class out, which is from the package System.



```
#include <stdio.h>
int main(int argc, char **argv) {
  /* greet user */
  printf("Hello World!\n");
  return 0:
```

C: To use the function printf(), the library stdio.h is included by the preprocessor instruction #include.

The most famous program of the world in **Java**

```
import java.lang.System;
class Hello {
  public static void main(String[] args) {
    /* greet user */
    System.out.println("Hello World!");
    return:
```

Java: To use the class out, the package System is included by the import instruction.





```
#include <stdio.h>
int main(int argc, char **argv) {
  /* greet user */
  printf("Hello World!\n");
  return 0:
```

C: Return to the operating system with return value 0 in this case indicates that no error has happened.

The most famous program of the world in **Java**

```
import java.lang.System;
class Hello {
  public static void main(String[] args) {
    /* greet user */
    System.out.println("Hello World!");
    return:
```

Java: Return to the operating system.



print('Hello World')



print('Hello World')

Python

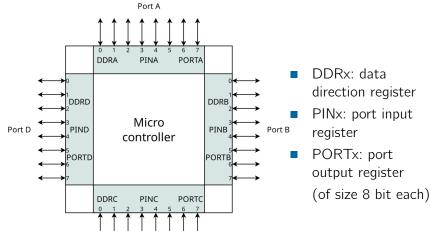
- Usually execution in interpreter
- High-level abstraction level
- Numerous built-in functions
- No explicit include directive required for built-in function

- Native execution on machine
- No interpreter required
- Machine orientation
- Explicit include statements for used functions



The First C Program for a μController

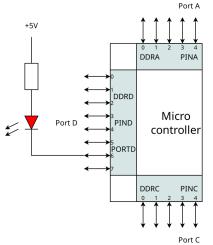
Preliminary information:



Port C

The First C Program for a µController

Background information:



- I ED is not lit:
 - DDRD bit 6: '1' (output)
 - PORTD bit 6: '1' (5V)
- LED lights up:
 - DDRD bit 6: '1' (output)
 - PORTD bit 6: '0' (0V)



```
#include <avr/io.h>
void main(void) {
 /* initialize hardware: LED on port D pin 6, active low */
        |= (1<<6); /* PD6 is used as output */
 DDRD
 PORTD |= (1<<6); /* PD6: high --> LED is off */
 /* greet user */
 PORTD &= ~(1<<6); /* PD6: low --> LED is on */
 /* wait forever */
 while (1) {
```



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#include <avr/io.h>
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Compilation and **flashing** (with SPiC-IDE)

→ Exercises





"Hello world" for AVR ATmega (SPiCboard)

```
#include <avr/io.h>
void main(void) {
 /* initialize hardware: LED on port D pin 6, active low */
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Compilation and **flashing** (with SPiC-IDE)

→ Exercises

Execution (SPiCboard):













(red LED lit)



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"Hello world" for AVR ATmega (SPiCboard)

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#include <avr/io.h>
void main(void) {
 /* initialize hardware: LED on port D pin 6, active low */
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 PORTD |= (1 << 6); /* PD6: high --> LED is off */
 /* greet user */
 PORTD &= ~(1<<6); /* PD6: low --> LED is on */
 /* wait forever */
 while (1) {
                                 µController programming is
                                 "somewhat different".
```

Compilation and **flashing** (with SPiC-IDE)

→ Exercises

Execution (SPiCboard):













(red LED lit)



```
#include <avr/io.h>
void main(void) {
 /* initialize hardware: LED on port D pin 6, active low */
  DDRD \mid = (1 << 6); /* PD6 is used as output */
  PORTD |= (1<<6); /* PD6: high --> LED is off */
 /* areet user */
  PORTD &= ~(1<<6); /* PD6: low --> LED is on */
 /* wait forever */
 while (1) {
```

The main()-function has no return value (type void). A μController program runs indefinitely ~ main() does not terminate.



```
#include <avr/io.h>
void main(void) {
 /* initialize hardware: LED on port D pin 6, active low */
        |= (1<<6); /* PD6 is used as output */
 DDRD
 PORTD |= (1<<6); /* PD6: high --> LED is off */
 /* areet user */
 PORTD &= ~(1<<6); /* PD6: low --> LED is on */
 /* wait forever */
 while (1) {
```

There will be **no return** to an operating system (which one?). The endless loop assures that main() does not terminate.



```
#include <avr/io.h>
void main(void) {
 /* initialize hardware: LED on port D pin 6, active low */
  DDRD \mid = (1 << 6); /* PD6 is used as output */
  PORTD |= (1<<6); /* PD6: high --> LED is off */
 /* areet user */
  PORTD &= ~(1<<6); /* PD6: low --> LED is on */
 /* wait forever */
 while (1) {
```

First, the **hardware** is initialized (i. e., put in a predefined state). For this, **single bits** in certain **hardware** registers have to be changed.



```
#include <avr/io.h>
void main(void) {
 /* initialize hardware: LED on port D pin 6, active low */
        |= (1<<6); /* PD6 is used as output */
 DDRD
 PORTD |= (1<<6); /* PD6: high --> LED is off */
 /* areet user */
 PORTD &= ~(1<<6): /* PD6: low --> LED is on */
 /* wait forever */
 while (1) {
```

The interaction with the environment (in this case: switching on the LED) takes place by manipulating single bits in hardware registers.



```
#include <avr/io.h>
void main(void) {
 /* initialize hardware: LED on port D pin 6, active low */
        |= (1<<6); /* PD6 is used as output */
 DDRD
 PORTD |= (1<<6); /* PD6: high --> LED is off */
 /* areet user */
 PORTD &= \sim(1<<6); /* PD6: low --> LED is on */
 /* wait forever */
 while (1) {
```

To access the hardware registers (DDRD, PORTD, provided as **global variables**), the **library** avr/io.h is included with #include.



user interaction (reading one character) with Linux:

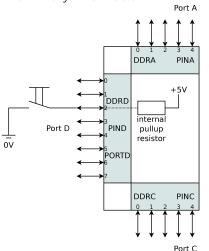
```
#include <stdio.h>
int main(int argc, char **argv) {
  printf("Press key: ");
  char key = getchar();
  printf("You pressed %c\n", key);
  return 0;
}
```

user interaction (reading one character) with Linux:

```
#include <stdio.h>
int main(int argc, char **argv) {
  printf("Press key: ");
  char key = getchar();
  printf("You pressed %c\n", key);
  return 0:
```

The getchar()-function reads one character from the standard input (here: keyboard). The function "waits", if necessary, until a character is available.





- Initialising:
 - DDRD bit 2: '0' (input)
 - PORTD bit 2: '1' (pull-up switched on)
- Detection:
 - PIND bit 2: '1'
 - => button not pressed
 - PIND bit 2: '0'
 - => button pressed





```
#include <avr/io.h>
void main(void) {
  /* initialize hardware: button on port D pin 2 */
  DDRD &= \sim(1 << 2); /* PD2 is used as input */
  PORTD |= (1 << 2); /* activate pull-up: PD2: high */
  /* initialize hardware: LED on port D pin 6, active low */
  DDRD \mid= (1 << 6); /* PD6 is used as output */
  PORTD |= (1 << 6); /* PD6: high --> LED is off */
  /* wait until PD2 -> low (button is pressed) */
  while ((PIND >> 2) & 1) {
  /* greet user */
  PORTD &= \sim (1 << 6): /* PD6: low --> LED is on */
  /* wait forever */
  while (1) {
```



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klsw

```
#include <avr/io.h>
void main(void) {
  /* initialize hardware: button on port D pin 2 */
  DDRD &= \sim(1 << 2); /* PD2 is used as input */
  PORTD |= (1 << 2); /* activate pull-up: PD2: high */
  /* initialize hardware: LED on port D pin 6, active low */
        |= (1 << 6); /* PD6 is used as output */
  DDRD
  PORTD |= (1 << 6); /* PD6: high --> LED is off */
  /* wait until PD2 -> low (button is pressed) */
  while ((PIND >> 2) & 1) {
                                                      Just like the LED, the button
                                                      is connected to a digital IO
                                                      pin of the uController. We
  /* greet user */
  PORTD &= ~(1 << 6); /* PD6: low --> LED is on */ now configure pin 2 at port
                                                      D as an input by clearing
  /* wait forever */
                                                      the corresponding bits in the
  while (1) {
                                                      register DDRD.
```

```
#include <avr/io.h>
void main(void) {
  /* initialize hardware: button on port D pin 2 */
  DDRD &= \sim(1 << 2); /* PD2 is used as input */
  PORTD |= (1 << 2); /* activate pull-up: PD2: high */
  /* initialize hardware: LED on port D pin 6, active low */
  DDRD \mid= (1 << 6); /* PD6 is used as output */
  PORTD |= (1 << 6); /* PD6: high --> LED is off */
  /* wait until PD2 -> low (button is pressed) */
  while ((PIND >> 2) & 1) {
                                                      By setting bit 2 in the regis-
                                                      ter PORTD as 1, the internal
                                                      pull-up resistor (high resi-
  /* greet user */
  PORTD &= \sim(1 << 6); /* PD6: low --> LED is on */ stance) is activated. Which is
                                                      connected to V_{CC} \sim PD2 =
  /* wait forever */
                                                      hiah.
  while (1) {
```





```
#include <avr/io.h>
void main(void) {
  /* initialize hardware: button on port D pin 2 */
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        |= (1 << 6); /* PD6 is used as output */
  DDRD
  PORTD |= (1 << 6); /* PD6: high --> LED is off */
  /* wait until PD2 -> low (button is pressed) */
  while ((PIND >> 2) & 1) {
                                                       Active waiting: waits for a
                                                       button to be pressed, i. e.,
                                                       while PD2 (bit 2 in the regis-
  /* greet user */
  PORTD &= \sim(1 << 6); /* PD6: low --> LED is on */ ter PIND) is high. When the
                                                       button is pressed, PD2 is pul-
  /* wait forever */
                                                       led to ground → bit 2 in the
  while (1) {
                                                       register PIND is now low and
                                                       the loop is exited.
```

```
import java.lang.System;
import iavax.swing.*:
import iava.awt.event.*:
public class Input implements ActionListener {
 private JFrame frame;
  public static void main(String[] args) {
   // create input, frame and button objects
    Input input = new Input();
    input.frame = new JFrame("Java Program");
    JButton button = new JButton("Press me"):
   // add button to frame
   input.frame.add(button);
    input.frame.setSize(400, 400);
    input.frame.setVisible(true);
    // register input as listener of button events
    button.addActionListener(input):
  public void actionPerformed(ActionEvent e) {
    System.out.println("Button pressed!");
   System.exit(0):
```



```
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```

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import java.lang.System;
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    // register input as listener of button events
    button.addActionListener(input):
  public void actionPerformed(ActionEvent e) {
    System.out.println("Button pressed!");
   System.exit(0):
```

The class Input implements an interface to receive interaction events.



```
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```

```
import java.lang.System;
import iavax.swing.*:
import iava.awt.event.*:
public class Input implements ActionListener {
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    input.frame.setVisible(true);
    // register input as listener of button events
    button.addActionListener(input):
  public void actionPerformed(ActionEvent e) {
    System.out.println("Button pressed!"):
   System.exit(0):
```

The program behaviour is implemented with the help of a multitude of **objects** (frame, button, input), which are created during initialization.



```
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```

```
import java.lang.System;
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    button.addActionListener(input):
  public void actionPerformed(ActionEvent e) {
    System.out.println("Button pressed!");
   System.exit(0):
```

The created **button**-object sends a message to the **input**-object.



```
03-Java-vs-C
```

```
import java.lang.System;
import javax.swing.*;
import iava.awt.event.*:
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    // register input as listener of button events
    button.addActionListener(input):
  public void actionPerformed(ActionEvent e) {
    System.out.println("Button pressed!"):
   System.exit(0):
```

The button press is signaled by an actionPerformed()-message (method call).



03-Java-vs-C

- The program cannot be compared to its counterpart in C directly.
 - It uses the (already known to you) **object-oriented paradigm**, which is typical for Java.
 - This difference shall be emphasised here.
- User interaction in Java explained line by line

The button press is signaled by an actionPerformed()-message (method call).

- Java/Python and C have similar **syntax** (Syntax: "What do valid programs of the language look like?")
- C syntax was used as a reference for the development of Java/Python
 - → many language elements are similar or identical
 - blocks, loops, conditions, statements, literals
 - these elements will be looked at in detail in the following chapters
- Major elements from Java/Python are **not** present in C
 - classes, packages, objects, exceptions, . . .



There are major **idiomatic** differences (Idiomatic: "What do programs of the language usually look like?")

Java: object-oriented paradigm

- Central question: From which things is a problem made of?
- Segmentation of the problem in classes and objects
- Hierarchy by inheritance and aggregation
- Program flow by interaction between objects
- Re-usability through extensive class libraries

C: imperative paradigm

- Central question: From which steps is the problem made up?
- Segmentation of the problem in **functions** and variables
- Hierarchy by breakdown into functions
- Program flow through calls between functions
- Re-usability through function libraries



- There are **philosophical** differences as well (Philosophy: "Basic ideas and concepts of a language")
- **Java:** Security and portability due to **abstracting from machine**
 - Compilation for virtual machines (JVM)
 - Extensive checks for programming errors during runtime
 - range overflow, division by 0, . . .
 - Problem-centric memory model
 - Only type-safe memory accesses, automatic garbage collection during runtime.
- C: efficiency and lightweight due to machine orientation
 - Compilation for concrete hardware architecture
 - No checks for programming errors during runtime
 - some error are caught by the operating system if present
 - Memory model directly maps to the machine
 - pointers provide direct memory access
 - coarse-grained access protection and automatic garbage collection (at processor level) by an OS – if present



 $C \mapsto$ machine orientation $\mapsto \mu C$ programming The machine orientation of the language C especially shows when looking at μC ontroller programming!

- Only one program is running
 - On RESET the program is loaded directly from flash memory
 - Hardware has to be initialized by the program first
 - Shall never terminate (e.g., with the help of a infinite loop in main())
- The solution is implemented close to the machine
 - Direct manipulation of single bits in hardware registers
 - Therefore detailed knowledge of *electrical wiring* is needed
 - No support of an operating system (like Linux)
 - Usually a low level of abstraction \sim error-prone... but fast



$C \mapsto \text{machine orientation} \mapsto \mu C \text{ programming}$

The machine orientation of the language C especially shows when looking at µController programming!

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 - Therefore detailed knowledge of *electrical wiring* is needed
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 - Usually a low level of abstraction ~> error-prone... but fast

Approach: Higher abstraction with problem-oriented libraries



